

Exploring the BBRv2 Congestion Control Algorithm for use on Data Transfer Nodes

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TCP Congestion Control 40+ year History

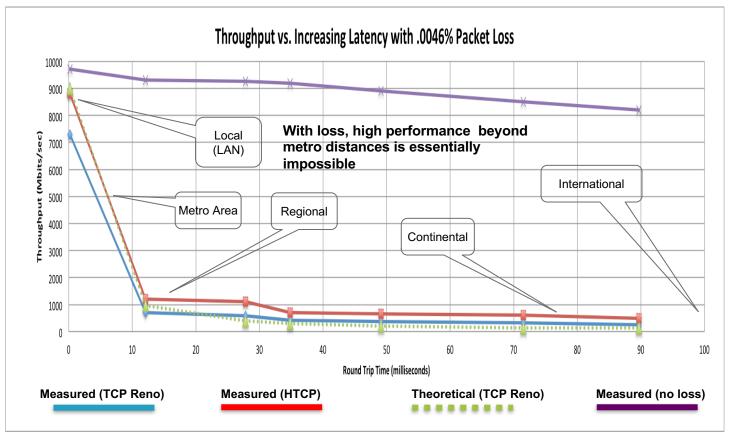
- 1981 Base specification [RFC 793]
- 1986: TCP Reno (First appeared in BSD4.3)
- 1988 Van Jacobson's landmark TCP paper
- 1996: "Mathis Equation" paper defining relationship between loss and bandwidth
- 1997: TCP Slow Start, Congestion Avoidance, Fast Retransmit, and Fast Recovery (RFC2001)
- 1999: New Reno (RFC 2582)
- 2004: Cubic TCP released
- 2005: Fast TCP and Hamilton TCP (H-TCP) released
- 2006: Cubic becomes the default in Linux
- 2013: ESnet's TCP slide motivation for a Science DMZ (next slide)
- 2013: FQ traffic shaper added to Linux
- 2016: BBRv1 (Bottleneck Bandwidth and Round-trip propagation time)
- 2019: BBRv2

See Matt Mathis's talk from March 2020 for excellent summary of TCP congestion control history

https://www.es.net/science-engagement/ci-engineering-lunch-and-learn-series



A small amount of packet loss makes a huge difference in TCP performance: BBR addresses this





TCP Congestion Control

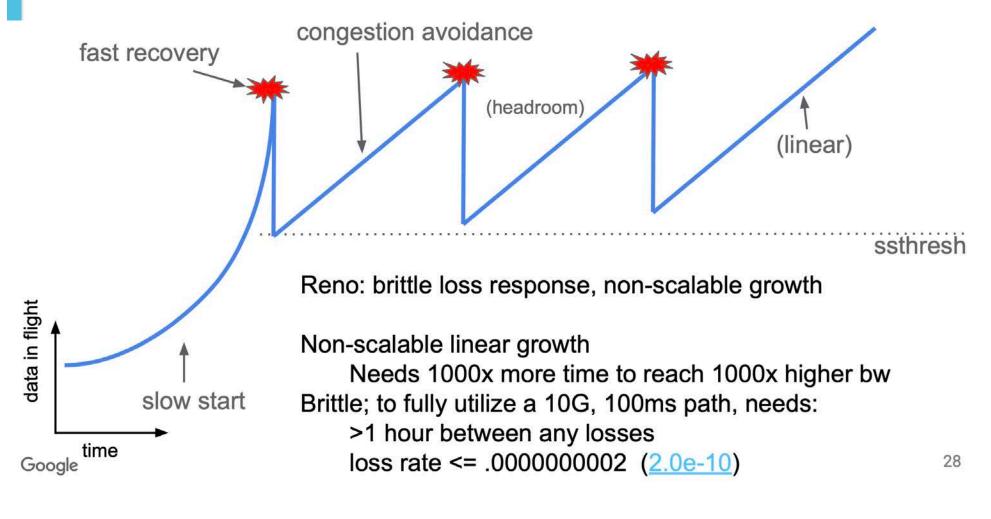
- Congestion Control Algorithms fall into 2 general categories:
 - Loss-based. (e.g.: Reno and Cubic)
 - Sender slows down if loss is detected
 - Delay-based (e.g.: Vegas and Fast)
 - Sender slows down if additional delay is detected
- The Internet has largely used loss-based congestion control algorithms
 - assumes that packet loss is equivalent to congestion
- But packet loss is not equivalent to congestion.
 - Congestion: network path has more data in flight than the bandwidth-delay product (BDP) of the path.
- Loss-based CC is increasing problematic due to:
 - Shallow buffers: in shallow buffers, packet loss happens before congestion
 - Deep buffers: at bottleneck links with deep buffers, congestion happens before packet loss.
- The BBR congestion control algorithm takes a different approach
 - Does not assume that packet loss = congestion,
 - BBR builds a model of the network path in order to avoid and respond to actual congestion.

BBR TCP (slide from Matt Mathis presentation, March 2020)

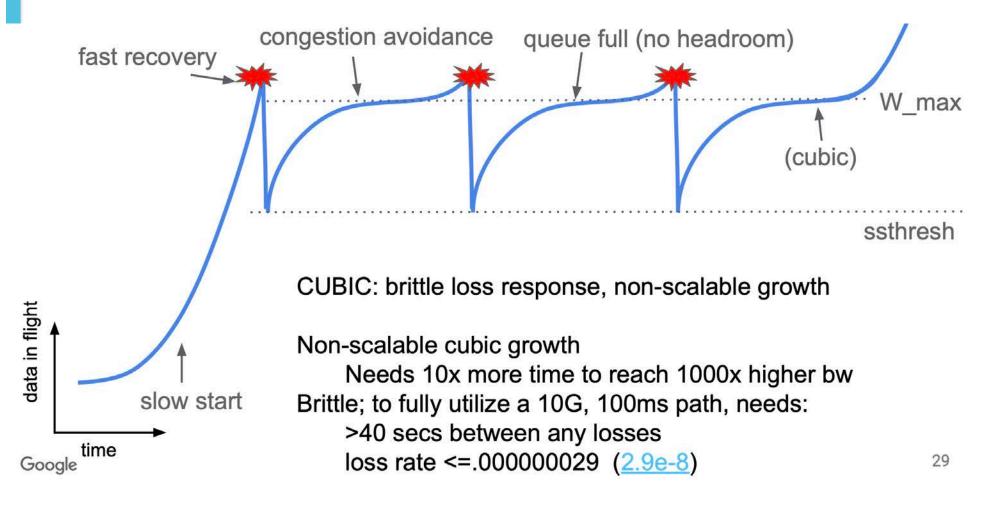
- BBR: new first principles for Congestion Control
 - BBR builds an explicit model of the network
 - Estimate max_BW and min_RTT
- The BBR core algorithm:
 - By default pace at a previously measured Max BW
 - Transmit based on a clock, not ACKs
 - Vary the pacing rate to measure model parameters
 - increase to observe new max rates
 - decrease to observe the min RTT
 - gather other signals such as ECN (bbr2)
- BBR's "personality" is determined by the heuristics used to vary the rates and perform the measurements
 - These heuristics are completely unspecified by the core algorithm
 - Relatively easy to extend or adapt
 - Many different heuristics algorithms can work in together



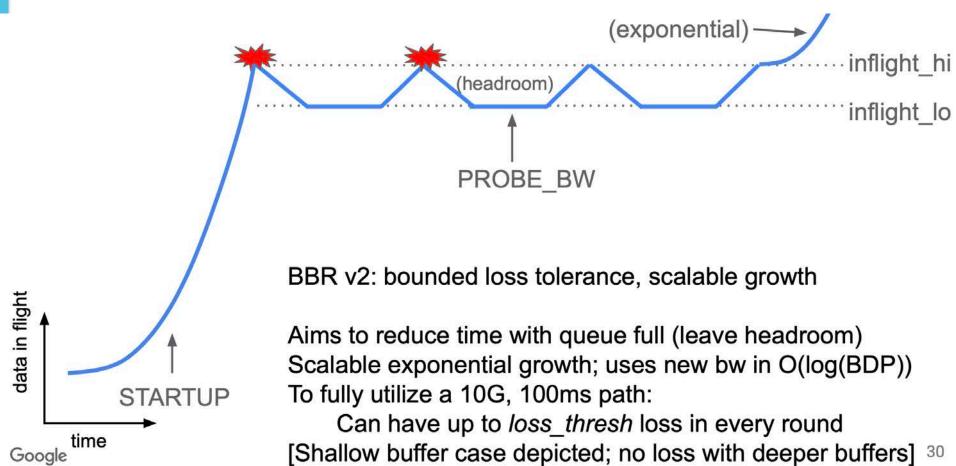
Reno



Cubic



Google



BBRv2 TCP

- Addresses the following BBRv1 issues
 - Low throughput for Reno/CUBIC flows sharing a bottleneck with bulk BBR flows
 - High packet loss rates if bottleneck queue < 1.5*BDP
 - Low throughput for paths with high degrees of aggregation (e.g. wifi)
 - Throughput variation due to low cwnd in PROBE_RTT
 - Adapts bandwidth probing for better coexistence with Reno/CUBIC
- https://datatracker.ietf.org/meeting/104/materials/slides-104-iccrg-an-update-on-bbr-00
- BBRv2 is currently being used on a small percentage of global YouTube traffic, and deployed as default TCP congestion control for internal Google traffic

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What's new in BBR v2: a summary

	CUBIC	BBR v1	BBR v2	
Model parameters to the state machine	N/A	Throughput, RTT	Throughput, RTT, max aggregation, max inflight	
Loss	Reduce cwnd by 30% on window with any loss	N/A	Explicit loss rate target	
ECN	RFC3168 (Classic ECN)	N/A	DCTCP-inspired ECN	
Startup	Slow-start until RTT rises (Hystart) or any loss	Slow-start until tput plateaus	Slow-start until tput plateaus or ECN/loss rate > target	

ESnet's BBRv2 Evaluation Project

Evaluate BBRv2 for large science data transfers

- 40G / 100G hosts ("Data Transfer Nodes")
- Data transfer tools that use parallel flows (e.g.: GridFTP)
- Focus is on R&E (research and education) networks, not commodity internet
 - Very different use case than Google/YouTube requirements
- Share results with protocol dev community and gather feedback
- Anticipate future small-buffer, high-BDP networks and wider adoption

Key question: will BBRv2 enable scientific applications to perform well in the absence of deep switch and router buffers?



BBRv2 has some assumptions 'baked in'

Comment in the BBRv2 source code:

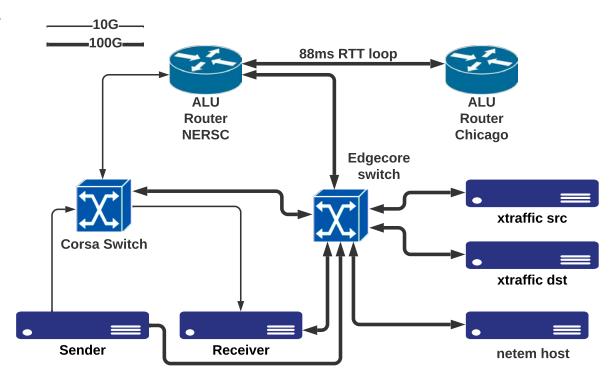
```
/*
 * We bound the Reno-coexistence inter-bw-probe time to be 62-63 round trips.
 * This is calculated to allow fairness with a 25Mbps, 30ms Reno flow,
 * (eg 4K video to a broadband user):
 * BDP = 25Mbps * .030sec /(1514bytes) = 61.9 packets
 */
```

- Our use case is quite different
 - Incoming DTN transfers to a ScienceDMZ will be a mix of BBR and CUBIC while BBR catches on
- Does BBRv2 work well for the DTN use case? How well does it coexist with CUBIC flows?



Testing Methodology

- Run Tests in a controlled environment
 - ESnet Testbed
- Run Tests over the Internet:
 - Using perfSONAR



ESnet Testbed Configuration



'real world' Testing

Source Node:

- 40G host directly connected to ESnet backbone
- Ubuntu 20, 5.10.0 kernel with bbr2 patches
- perfSONAR Testpoint Docker container
 - https://docs.perfsonar.net/install options.html
 - perfSONAR only allows 1 throughput test to be run at a time

Destination Nodes:

- There are roughly 2000 registered perfSONAR hosts worldwide
 - most of which allow testing from ESnet
 - many of which allow testing from anywhere
 - most restrict testing to 1 minute, but ESnet allows longer tests from other ESnet hosts.
- Tests are running on production networks, with no control over competing traffic
- We selected a variety of test hosts of various RTTs and various loss characteristics



Test Harness

- Python program to facilitate running tests and collecting instrumentation data.
- Sample config file entry:

```
[pscheduler_bbr2_p16]
type = perfSONAR
enabled = true
iterations = 10
src = localhost
dst = 10.201.1.2
src-cmd = pscheduler task --format json throughput --congestion=bbr2 --
ip-version 4 --parallel 16 --duration PT5M --dest {dst}
pre-src-cmd = /usr/sbin/sysctl -w net.ipv4.tcp_congestion_control=bbr2
post-src-cmd = /usr/sbin/sysctl -w net.ipv4.tcp_congestion_control=cubic
tcpdump = true
tcpdump-filt = -s 128 -i ens2np0 "host {dst} and port 5201"
netem-loss = 0.001
lat-sweep = 2,5,10,20,30,50
pacing = 2.4gbit
```

Raw Data

Our test harness has the ability to collect the following:

- iperf3 JSON output (as reported by pscheduler tool)
- ss (socket stats)
- tcpdump / tcptrace
- mpstat (CPU load)

The data used to generate these plots is available at:

https://downloads.es.net/INDIS-2021/

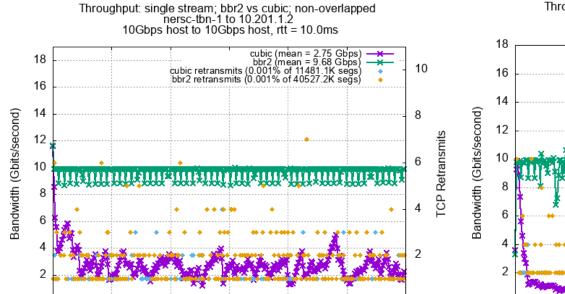


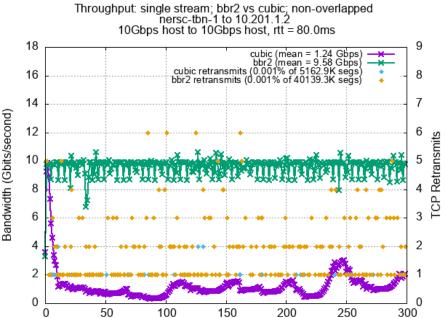
Testing / Plotting Methodology and Terminology

- Parallel Flow tests all use 16 flows
 - This is a common default for Globus and other DTN tools
- "non-overlapped" means a 16 flow CUBIC test, followed by a 16 flow BBRv2 test
- "overlapped" means 8 CUBIC flows and 8 BBRv2 flows, all at the same time
- Netem-based results have netem setting in the lower right of the plot



Single flow results: BBRv2 vs CUBIC, 0.001% packet loss





• For single flows, BBRv2 does much better than CUBIC on paths, even with low (0.001%) packet loss

Data Dir: 2021-06-02:14:50

300

netem delay 5 ms, loss rate 0.001%

BBRv2 advantage increases with longer RTT

100

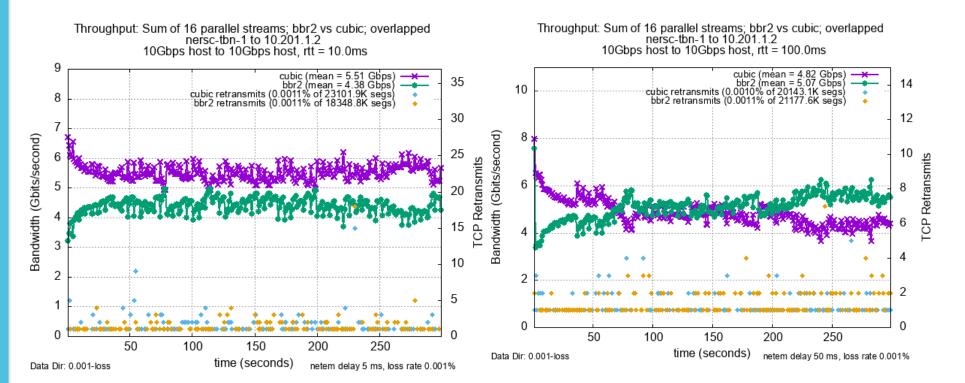
Data Dir: 2021-06-02:18:43

150

time (seconds)

time (seconds) netem delay 40 ms, loss rate 0.001%

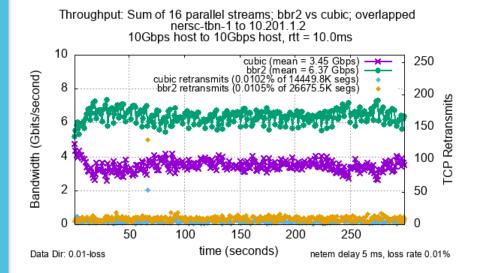
16 flow results: BBRv2 vs CUBIC, 0.001% packet loss

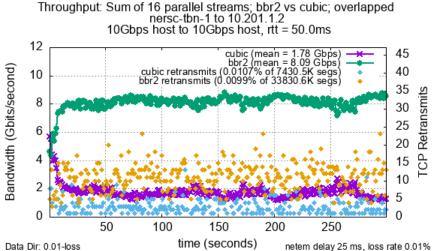


Parallel CUBIC flows compensate for BBRv2's advantage for low packet loss rates. BBRv2 and CUBIC throughputs are similar.



16 flow results: BBRv2 vs CUBIC, 0.01% packet loss

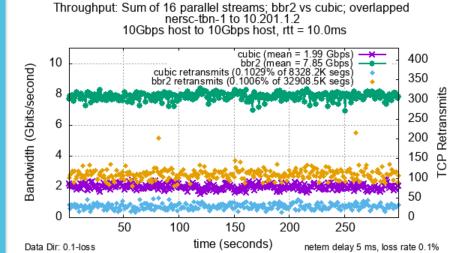


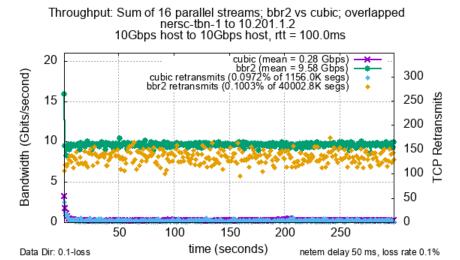


With additional packet loss (0.01%) parallel BBRv2 starts to do much better than CUBIC, especially on long paths



16 flow results: BBRv2 vs CUBIC, 0.1% packet loss





BBRv2 does even better yet with 0.1% loss. 4x better on a 10ms path, and more than 30x faster on a 100ms path

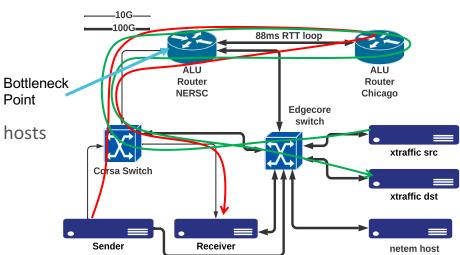


Buffer Size results

TCP over 10G 88ms loop path (red line)

Background 1 Gbps UDP stream between testbed hosts xtraffic src/dst to create congestion (green line)

Adjusted buffer size on Corsa Switch



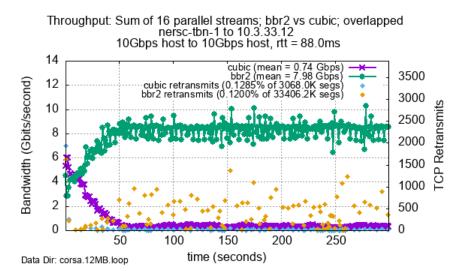
Buffer Size	CUBIC throughput	BBRv2 throughput			
8 MB	0.4 Gbps	8.3 Gbps			
12 MB	0.9 Gbps	8.0 Gbps			
16 MB	1.8 Gbps	6.9 Gbps			
32 MB	4.5 Gbps	4.3 Gbps			
64 MB	4.6 Gbps	4.2 Gbps			

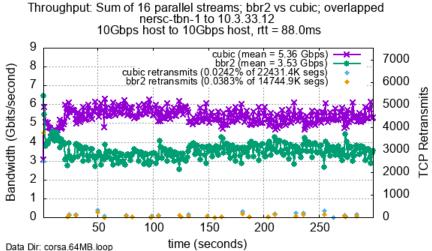
Point

Summary: BBRv2 does much better with smaller buffers **CUBIC** does slightly better with large buffers



Switch Buffer Size testing (Testbed results)



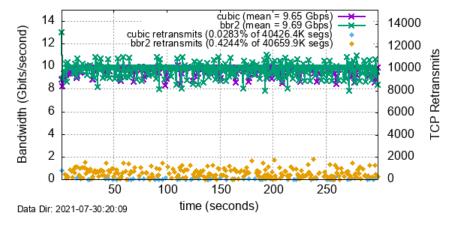


- 12 MB buffers on the left, 64 MB buffers on the right
- BBRv2 does much better with small buffers
- CUBIC does better with large buffers



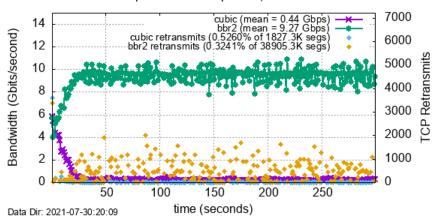
16 flow results: Testbed, 100G sender to 10G receiver

Throughput: sum of 16 parallel streams; bbr2 vs cubic; non-overlapped nersc-tbn-1 to 10.10.33.12
100Gbps host to 10Gbps host, rtt = 88.0ms



 BBRv2 and CUBIC both do well on a clean path, but BBRv2 retransmit rate is consistently about 20x higher than CUBIC

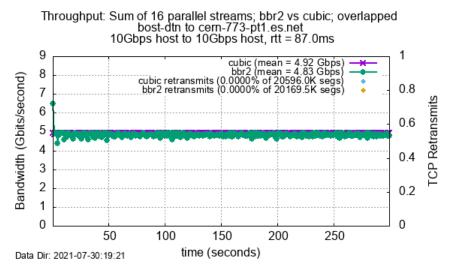
Throughput: Sum of 16 parallel streams; bbr2 vs cubic; overlapped nersc-tbn-1 to 10.10.33.12 100Gbps host to 10Gbps host, rtt = 88.0ms



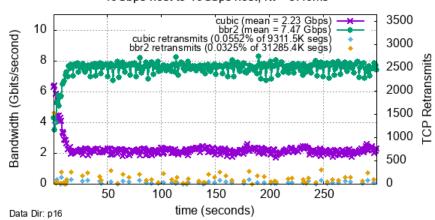
 With overlapped flows, BBRv2 steps on CUBIC flows, is 20 times faster, and has fewer retransmits.



16 flow results: ESnet results, 40G to 10G



Throughput: Sum of 16 parallel streams; bbr2 vs cubic; overlapped bost-dtn to cern-773-pt1.es.net 40Gbps host to 10Gbps host, rtt = 87.0ms



10G sender (620 Mbps pacing/flow, 9.9G total)

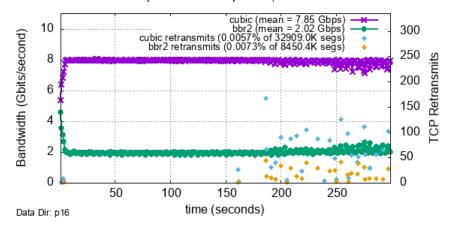
40G sender (2.4 Gbps pacing/flow, 38.4G total)

- No speed mismatch = No packet loss = CUBIC and BBRv2 are equivalent
- But BBRv2 does much better when sender is faster than receiver



But, Sometimes CUBIC is a lot faster....

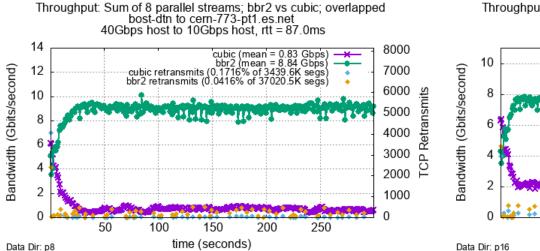
Throughput: Sum of 16 parallel streams; bbr2 vs cubic; overlapped bost-dtn to aofa-pt1.es.net 40Gbps host to 10Gbps host, rtt = 5.0ms

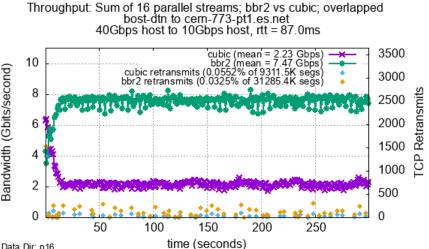


- Overlapped CUBIC and BBR2 flows
- 5ms RTT, low packet loss
- CUBIC is considerably faster
- Note: very deep buffers on this path



How many parallel flows?

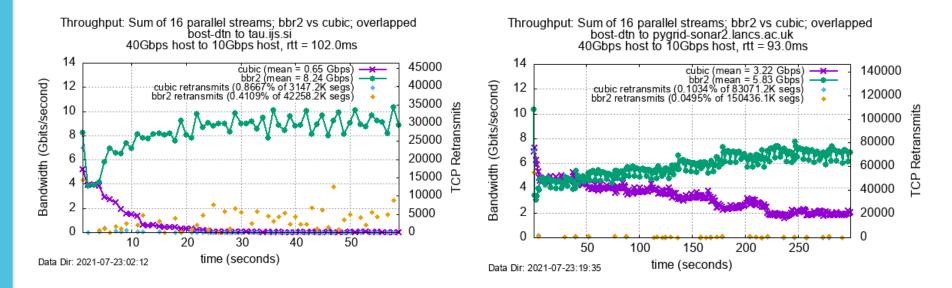




- CUBIC benefits from additional flows, BBRv2 does not
- Initial testing shows that maximum BBRv2 throughput is achieved with 2-4 flows; (more testing needed)



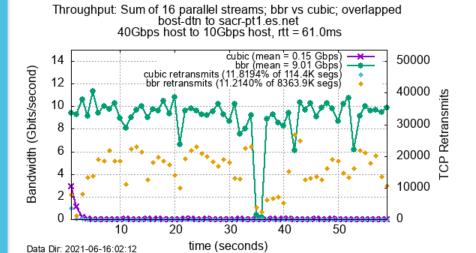
BBRv2 gains greater share of the pipe over time

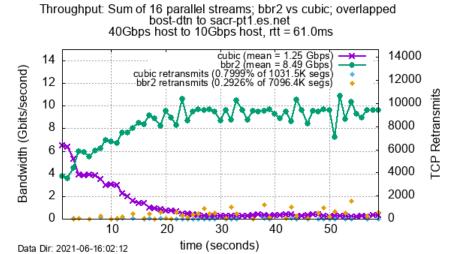


• Sometimes this happens in the 1st 20 seconds of the flow, and sometimes not until much later.



BBRv2 vs BBRv1





BBRv1 has way more retransmits and is way more unfriendly to CUBIC

- CUBIC only gets 0.15Gbps, vs 1.25Gbps with BBRv2
- Retransmits > 11% for BBRv1, and < 1% for BBRv2



Fairness to CUBIC

- Under some circumstances, BBRv2 is "unfair" to CUBIC
 - High-BDP paths with packet loss (e.g. from shallow buffer switch or congestion)
 - Speed mismatch (e.g. 100G host to 10G host)
- In theory, it is useful to study fairness, because it helps us understand protocols
- In practice, CUBIC requires very expensive engineering to be competitive with BBRv2
 - Very low packet loss requires deep buffers, significant human effort especially for high-BDP environments (e.g. science/DTN workloads)
 - How should we account for the difference in cost to achieve "fairness?"
- Practical deployment concerns are likely to favor the adoption of BBRv2 and the phase-out of CUBIC over time

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Next Steps

- 100G Testing
 - o Are there any surprises at 100G?
- More buffer testing with other small buffered devices
- Testing of BBR QUIC and maybe BIG TCP
- Testing of next release of BBRv2?



Key Takeaways

- BBR (both v1 and v2) does much better than CUBIC on lossy paths
 - The higher the loss rate and RTT, the more BBR wins out.
- Faster hosts sending parallel flows to slower hosts leads to packet loss
 - BBR does much better than CUBIC in this situation.
- The BBRv1 retransmit rate is unacceptably high with parallel flows, and is very unfair to CUBIC
 - BBRv1 should not be used with parallel data transfer applications.
- BBR prefers smaller switch buffers, and CUBIC prefers larger buffers.
 - As network interface speed increases, larger and larger buffers are impractical (and thus more expensive)
 - Therefore BBR will be a better choice in the future.



Run your own tests

- Install BBR kernel patch: https://github.com/google/bbr/blob/v2alpha/README.md
- Customized Docker container for running your own perfSONAR testpoint on a bbr2 enabled host:
 - https://hub.docker.com/r/dtnaas/perfsonar-testpoint
- Test harness source code:
 - https://github.com/esnet/testing-harness



For more information

- BBRv2:
 - https://groups.google.com/g/bbr-dev
 - Links to all of Google's BBR papers and talks can be found there.
- Relevant pages on FasterData:
 - https://fasterdata.es.net/science-dmz/DTN/tuning/
 - https://fasterdata.es.net/network-tuning/packet-pacing/
- INDIS SC21 paper: https://ieeexplore.ieee.org/document/9652571
 - All data collected for this paper are available at
 - https://downloads.es.net/INDIS-2021/.
 - This includes output from *iperf3* and *ss*, as well at the gnuplot files used to generate the plots in the INDIS paper.





Extra Slides





BBRv2 Tuning Parameters

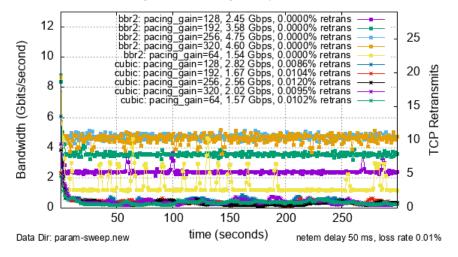
Lots of tuning knobs (/sys/module/tcp_bbr2/parameters/)

```
ack_epoch_acked_reset_thresh bw_probe_rand_us extra_acked_gain inflight_headroom probe_rtt_cwnd_gain bw_probe_reno_gain extra_acked_in_startup full_bw_cnt loss_thresh probe_rtt_mode_ms usage_based_cwnd bw_probe_base_us cwnd_gain ecn_factor extra_acked_max_us full_bw_thresh min_rtt_win_sec probe_rtt_win_ms bw_probe_max_rounds cwnd_min_target drain_gain ecn_max_rtt_us extra_acked_win_rtts full_ecn_cnt min_tso_rate refill_add_inc bw_probe_pif_gain cwnd_tso_bduget drain_to_target ecn_reprobe_gain fast_ack_mode full_loss_cnt pacing_gain startup_cwnd_gain bw_probe_rand_rounds cwnd_warn_val ecn_alpha_gain ecn_thresh fast_path high_gain precise_ece_ack tso_rtt_shift
```

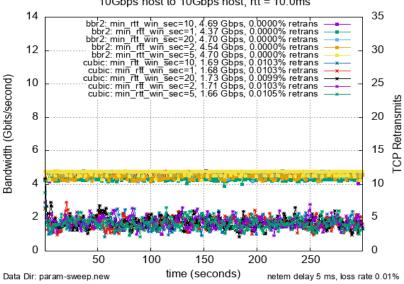


Parameter Sweep Results

Throughput: 4 parallel streams; bbr2 vs cubic; overlapped parameter sweep of pacing_gain (1), sum of 2 streams each nersc-tbn-1 to 10.201.1.2
10Gbps host to 10Gbps host, rtt = 100.0ms







- Our test harness supports testing a range of BBRv2 parameters
- Results to date show that default settings appear optimal
- Much more testing is needed



Test Variability

- We ran 10 runs of each experiment configuration, and computed the coefficient of variation (CV) of each
 - CV is defined as the ratio of the standard deviation to the mean.
 - The higher the coefficient of variation, the greater the level of dispersion around the mean.
- The CV for all experiments was < 1 (i.e.: reasonable)
- BBRv2 results were 4-5 times more stable than CUBIC based on the CV
- See the paper for more details



Variance

TABLE II: COMPARING MEAN (M) & COEF. OF VARIANCE (C.V) FOR ESNET TESTBED.

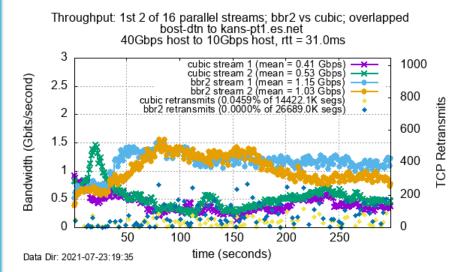
	RTT < 30ms				RTT ≥ 30ms				
Test		BBRv2		CUBIC		BBRv2		CUBIC	
		Mean	C.V.	Mean	C.V.	Mean	C.V.	Mean	C.V.
	bbrv2/cubic - p1	9.6533	0.0030	9.8799	0.0024	9.4749	0.0080	9.8435	0.0019
No loss	bbrv2/cubic - p16	9.7891	0.0064	9.8827	0.0007	9.8044	0.0039	9.8348	0.0029
ioss	both - p16	3.1188	0.1834	6.7642	0.0849	3.3604	0.0627	6.4739	0.0334
0.001.07	bbrv2/cubic - p1	9.6545	0.0021	3.3341	0.4694	9.4834	0.0073	1.2988	0.1541
0.001%	bbrv2/cubic - p16	9.7918	0.0061	9.8819	0.0008	9.7838	0.0041	9.7794	0.0071
loss	both - p16	4.2258	0.1360	5.6566	0.1026	4.9394	0.0390	4.8894	0.0435
0.01.07	bbrv2/cubic - p1	2.3477	0.0017	1.0500	0.5585	2.3041	0.0018	0.2454	0.0722
0.01%	bbrv2/cubic - p16	9.7586	0.0053	9.0397	0.1325	9.8131	0.0017	3.9534	0.0205
loss	both - p16	6.1650	0.1954	3.6777	0.3352	8.0112	0.0068	1.7950	0.0276
0.10/	bbrv2/cubic - p1	8.8108	0.0788	0.3308	0.5180	8.7230	0.0746	0.0472	0.2533
0.1%	bbrv2/cubic - p16	9.7969	0.0037	5.1883	0.5058	9.7824	0.0038	0.7438	0.2552
loss	both - p16	7.5959	0.1542	2.2361	0.5284	9.4057	0.0068	0.3652	0.2545
1000 . 100	bbrv2/cubic - p16	_	_	-	-	9.6275	0.0004	9.4377	0.0344
100G-to-10G	both - p16	_	-	-	-	9.2094	0.0028	0.4254	0.0473

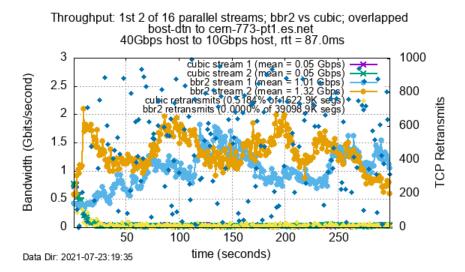
TABLE III: COMPARING M & C.V, BOST-DTN to ESNET & NON-ESNET HOSTS.

			RTT < 30ms				RTT ≥ 30ms			
Test		BBRv2		CUBIC		BBRv2		CUBIC		
		Mean	C.V.	Mean	C.V.	Mean	C.V.	Mean	C.V.	
10G-to-10G	ESNET	both - p16	4.7750	0.0726	5.0057	0.1122	4.7733	0.0055	4.8860	0.0043
10G-10-10G	NON-ESNET	both - p16	4.2526	0.0742	4.6333	0.0309	3.9346	0.2188	3.8361	0.2972
40G-to-10G	ESNET	both - p8	4.5768	0.2991	5.2852	0.2399	8.3485	0.0899	1.2883	0.6450
	ESINEI	both - p16	4.3490	0.2291	5.1557	0.1906	6.9421	0.1222	2.4023	0.3816
	NON-ESNET	both - p8	-	-	-	-	8.2697	0.0626	2.9697	0.2500
		both - p16	-	-	-	-	8.1870	0.1512	1.9163	0.6094



Parallel Stream Behavior



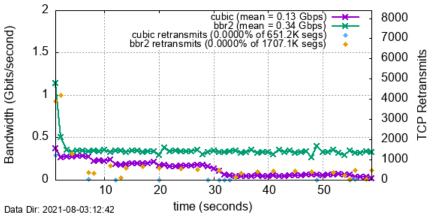


BBRv2 performance not very stable in this environment

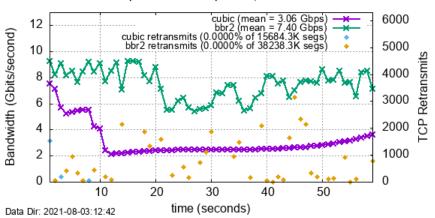


More Single Flow Examples



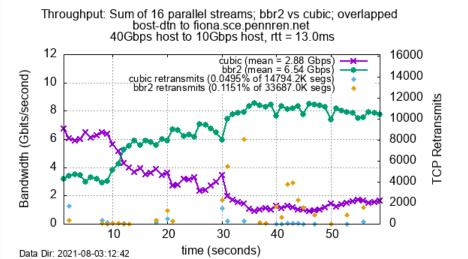


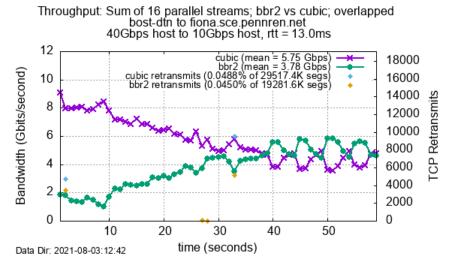
Throughput: single stream; bbr2 vs cubic; non-overlapped bost-dtn to pygrid-sonar2.lancs.ac.uk 40Gbps host to 10Gbps host, rtt = 93.0ms





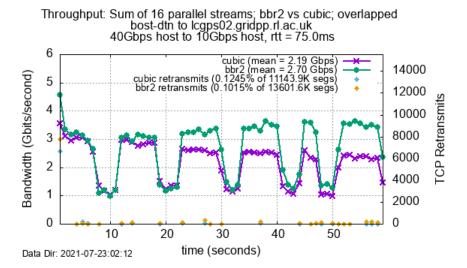
More 16-flow parallel examples: Some paths are odd...







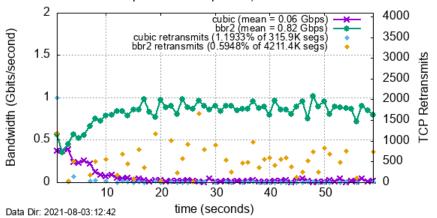
More 16-flow parallel examples: Some paths are odd..





More 16-flow parallel examples

Throughput: Sum of 16 parallel streams; bbr2 vs cubic; overlapped bost-dtn to btw-bw.t1.grid.kiae.ru 40Gbps host to 1Gbps host, rtt = 109.0ms



Throughput: Sum of 16 parallel streams; bbr2 vs cubic; overlapped bost-dtn to denv-pt1.es.net 40Gbps host to 10Gbps host, rtt = 41.0ms

